

## 提要 299：三個函數的 Jacobian 問題

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已知：

$$f(x, y, z, u, v, w) = C_1$$

$$g(x, y, z, u, v, w) = C_2$$

$$h(x, y, z, u, v, w) = C_3$$

試推求  $\frac{\partial u}{\partial x}$ 、 $\frac{\partial v}{\partial y}$ 、 $\frac{\partial w}{\partial z}$ 。

解答：

首先對  $f(x, y, z, u, v, w) = C_1$ 、 $g(x, y, z, u, v, w) = C_2$ 、 $h(x, y, z, u, v, w) = C_3$  作全微分 (Total Differential) 之運算，亦即：

$$\begin{cases} df(x, y, z, u, v, w) = dC_1 & (1a) \\ dg(x, y, z, u, v, w) = dC_2 & (1b) \\ dh(x, y, z, u, v, w) = dC_3 & (1c) \end{cases}$$

上式可改寫為：

$$\begin{cases} \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz + \frac{\partial f}{\partial u} du + \frac{\partial f}{\partial v} dv + \frac{\partial f}{\partial w} dw = 0 & (2a) \\ \frac{\partial g}{\partial x} dx + \frac{\partial g}{\partial y} dy + \frac{\partial g}{\partial z} dz + \frac{\partial g}{\partial u} du + \frac{\partial g}{\partial v} dv + \frac{\partial g}{\partial w} dw = 0 & (2b) \\ \frac{\partial h}{\partial x} dx + \frac{\partial h}{\partial y} dy + \frac{\partial h}{\partial z} dz + \frac{\partial h}{\partial u} du + \frac{\partial h}{\partial v} dv + \frac{\partial h}{\partial w} dw = 0 & (2c) \end{cases}$$

由式(2a)-(2c)分別對  $x$ 、 $y$ 、 $z$  微分，可分別推求出：

$$\begin{cases} \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial x} + \frac{\partial f}{\partial z} \frac{\partial z}{\partial x} + \frac{\partial f}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial f}{\partial v} \frac{\partial v}{\partial x} + \frac{\partial f}{\partial w} \frac{\partial w}{\partial x} = 0 & (3a) \\ \frac{\partial g}{\partial x} \frac{dx}{dx} + \frac{\partial g}{\partial y} \frac{\partial y}{\partial x} + \frac{\partial g}{\partial z} \frac{\partial z}{\partial x} + \frac{\partial g}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial g}{\partial v} \frac{\partial v}{\partial x} + \frac{\partial g}{\partial w} \frac{\partial w}{\partial x} = 0 & (3b) \\ \frac{\partial h}{\partial x} \frac{dx}{dx} + \frac{\partial h}{\partial y} \frac{\partial y}{\partial x} + \frac{\partial h}{\partial z} \frac{\partial z}{\partial x} + \frac{\partial h}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial h}{\partial v} \frac{\partial v}{\partial x} + \frac{\partial h}{\partial w} \frac{\partial w}{\partial x} = 0 & (3c) \end{cases}$$



$\frac{\partial f}{\partial w} = f_w$ 、 $\frac{\partial g}{\partial x} = g_x$ 、 $\frac{\partial g}{\partial y} = g_y$ 、 $\frac{\partial g}{\partial z} = g_z$ 、 $\frac{\partial g}{\partial u} = g_u$ 、 $\frac{\partial g}{\partial v} = g_v$ 、 $\frac{\partial g}{\partial w} = g_w$ ，則式(6a)-(6c)、(7a)-(7c)、(8a)-(8c)又可改寫為：

$$\left\{ \begin{array}{l} f_u \frac{\partial u}{\partial x} + f_v \frac{\partial v}{\partial x} + f_w \frac{\partial w}{\partial x} = -f_x \\ g_u \frac{\partial u}{\partial x} + g_v \frac{\partial v}{\partial x} + g_w \frac{\partial w}{\partial x} = -g_x \\ h_u \frac{\partial u}{\partial x} + h_v \frac{\partial v}{\partial x} + h_w \frac{\partial w}{\partial x} = -h_x \end{array} \right. \quad \begin{array}{l} (9a) \\ (9b) \\ (9c) \end{array}$$

$$\left\{ \begin{array}{l} f_u \frac{\partial u}{\partial y} + f_v \frac{\partial v}{\partial y} + f_w \frac{\partial w}{\partial y} = -f_y \\ g_u \frac{\partial u}{\partial y} + g_v \frac{\partial v}{\partial y} + g_w \frac{\partial w}{\partial y} = -g_y \\ h_u \frac{\partial u}{\partial y} + h_v \frac{\partial v}{\partial y} + h_w \frac{\partial w}{\partial y} = -h_y \end{array} \right. \quad \begin{array}{l} (10a) \\ (10b) \\ (10c) \end{array}$$

$$\left\{ \begin{array}{l} f_u \frac{\partial u}{\partial z} + f_v \frac{\partial v}{\partial z} + f_w \frac{\partial w}{\partial z} = -f_z \\ g_u \frac{\partial u}{\partial z} + g_v \frac{\partial v}{\partial z} + g_w \frac{\partial w}{\partial z} = -g_z \\ h_u \frac{\partial u}{\partial z} + h_v \frac{\partial v}{\partial z} + h_w \frac{\partial w}{\partial z} = -h_z \end{array} \right. \quad \begin{array}{l} (11a) \\ (11b) \\ (11c) \end{array}$$

式(9a)-(9c)、式(10a)-(10c)與式(11a)-(11c)可分別表為：

$$\begin{bmatrix} f_u & f_v & f_w \\ g_u & g_v & g_w \\ h_u & h_v & h_w \end{bmatrix} \begin{bmatrix} \frac{\partial u}{\partial x} \\ \frac{\partial v}{\partial x} \\ \frac{\partial w}{\partial x} \end{bmatrix} = \begin{bmatrix} -f_x \\ -g_x \\ -h_x \end{bmatrix} \quad (12)$$

$$\begin{bmatrix} f_u & f_v & f_w \\ g_u & g_v & g_w \\ h_u & h_v & h_w \end{bmatrix} \begin{bmatrix} \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial y} \\ \frac{\partial w}{\partial y} \end{bmatrix} = \begin{bmatrix} -f_y \\ -g_y \\ -h_y \end{bmatrix} \quad (13)$$

$$\begin{bmatrix} f_u & f_v & f_w \\ g_u & g_v & g_w \\ h_u & h_v & h_w \end{bmatrix} \begin{bmatrix} \frac{\partial u}{\partial z} \\ \frac{\partial v}{\partial z} \\ \frac{\partial w}{\partial z} \end{bmatrix} = \begin{bmatrix} -f_z \\ -g_z \\ -h_z \end{bmatrix} \quad (14)$$

應用 Cramer 定則解析式(12)，即可推求出  $\frac{\partial u}{\partial x}$  之解：

$$\frac{\partial u}{\partial x} = \frac{\begin{vmatrix} -f_x & f_v & f_w \\ -g_x & g_v & g_w \\ -h_x & h_v & h_w \end{vmatrix}}{\begin{vmatrix} f_u & f_v & f_w \\ g_u & g_v & g_w \\ h_u & h_v & h_w \end{vmatrix}} = -\frac{\begin{vmatrix} f_x & f_v & f_w \\ g_x & g_v & g_w \\ h_x & h_v & h_w \end{vmatrix}}{\begin{vmatrix} f_u & f_v & f_w \\ g_u & g_v & g_w \\ h_u & h_v & h_w \end{vmatrix}} = -\frac{J\left(\frac{f, g, h}{x, v, w}\right)}{J\left(\frac{f, g, h}{u, v, w}\right)} \quad (15)$$

同理，應用 Cramer 定則解析式(13)，即可推求出  $\frac{\partial v}{\partial y}$  之解：

$$\frac{\partial v}{\partial y} = \frac{\begin{vmatrix} f_u & -f_y & f_w \\ g_u & -g_y & g_w \\ h_u & -h_y & h_w \end{vmatrix}}{\begin{vmatrix} f_u & f_v & f_w \\ g_u & g_v & g_w \\ h_u & h_v & h_w \end{vmatrix}} = -\frac{\begin{vmatrix} f_u & f_y & f_w \\ g_u & g_y & g_w \\ h_u & h_y & h_w \end{vmatrix}}{\begin{vmatrix} f_u & f_v & f_w \\ g_u & g_v & g_w \\ h_u & h_v & h_w \end{vmatrix}} = -\frac{J\left(\frac{f, g, h}{u, y, w}\right)}{J\left(\frac{f, g, h}{u, v, w}\right)} \quad (16)$$

同理，應用 Cramer 定則解析式(14)，即可推求出  $\frac{\partial w}{\partial z}$  之解：

$$\frac{\partial w}{\partial z} = \frac{\begin{vmatrix} f_u & f_v & -f_z \\ g_u & g_v & -g_z \\ h_u & h_v & -h_z \end{vmatrix}}{\begin{vmatrix} f_u & f_v & f_w \\ g_u & g_v & g_w \\ h_u & h_v & h_w \end{vmatrix}} = -\frac{\begin{vmatrix} f_u & f_v & f_z \\ g_u & g_v & g_z \\ h_u & h_v & h_z \end{vmatrix}}{\begin{vmatrix} f_u & f_v & f_w \\ g_u & g_v & g_w \\ h_u & h_v & h_w \end{vmatrix}} = -\frac{J\left(\frac{f, g, h}{u, v, z}\right)}{J\left(\frac{f, g, h}{u, v, w}\right)} \quad (17)$$

附註：三個函數  $F$ 、 $G$ 、 $H$  之 Jacobian 是定義為

$$J\left(\begin{matrix} F, G, H \\ \alpha, \beta, \gamma \end{matrix}\right) = \begin{vmatrix} F_\alpha & F_\beta & F_\gamma \\ G_\alpha & G_\beta & G_\gamma \\ H_\alpha & H_\beta & H_\gamma \end{vmatrix}, \text{ 其中}$$

$$F_\alpha = \frac{\partial F}{\partial \alpha}, \quad F_\beta = \frac{\partial F}{\partial \beta}, \quad F_\gamma = \frac{\partial F}{\partial \gamma}, \quad G_\alpha = \frac{\partial G}{\partial \alpha}, \quad G_\beta = \frac{\partial G}{\partial \beta}, \quad G_\gamma = \frac{\partial G}{\partial \gamma}, \quad H_\alpha = \frac{\partial H}{\partial \alpha},$$

$$H_\beta = \frac{\partial H}{\partial \beta}, \quad H_\gamma = \frac{\partial H}{\partial \gamma} \text{。}$$